

Föreläsning 7

TMME04 – Mekanik II

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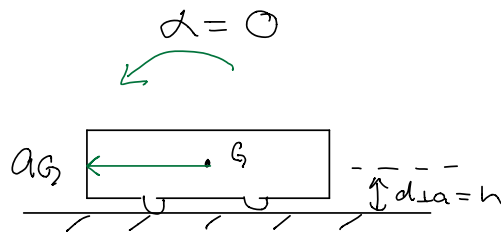
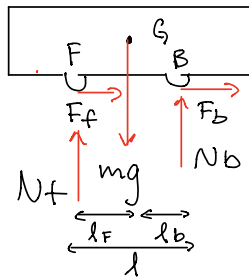
<https://www.instagram.com/olwettergren/>

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Söut: Max retardation för motorcykel

$$|F_{fr}| \leq \mu N$$

Frilägg



Euler I,

$$\vec{F} = m\vec{a}_G$$

$$\leftarrow : -F_f - f_b = m a_G \quad (1)$$

$$\uparrow : N_f + N_b - mg = 0 \quad (2)$$

Euler II, (skalärt)

$$M_B = I_G \alpha + m a_G d_{\perp a}$$

$$\vec{B} : N_f \cdot l - mg \cdot l_b = I_G \alpha - m a_G h = 0 - m a_G h \quad (3)$$

(1) och (3) \Rightarrow

$$N_f = mg \frac{l_b}{l} + \frac{F_f + F_b}{l} \cdot h \quad (4)$$

(2) \Rightarrow

$$N_b = \frac{mg}{l} (l - lb) - \frac{F_f + F_b}{l} \cdot h \quad (5)$$

Retardation, r .

$$r = -a_G = \overset{(1)}{\frac{F_f + F_b}{m}} \quad (6)$$

$$F_f \leq \mu N_f, \quad F_b \leq \mu N_b,$$

Så r_{\max} fås då

$$F_f = \mu N_f, \quad F_b = \mu N_b \quad (N_b > 0)$$

$$r_{\max} = \overset{(4), (5)}{\frac{\mu}{m}} \left(mg \frac{lb}{l} + mg \frac{(l-lb)}{l} \right) = \mu g$$

Måste ha $N_b > 0$

$$(5) \Rightarrow \frac{mg(l-lb)}{l} - \underbrace{\frac{F_f + F_b}{l} \cdot h}_{\stackrel{(6)}{=} \frac{\mu r h}{l}} > 0 \Leftrightarrow$$

$$r < \frac{l-lb}{h} \cdot g = \frac{l_f}{h} \cdot g$$

$$\therefore r_{\max} = \min \left(\mu g, \frac{l_f}{h} \cdot g \right)$$

Om $\mu > \frac{l_f}{h}$ begränsas alltså r_{\max} av tippning.

b) Sökt: $\frac{F_f}{F_{tot}}$,

$F_{tot} := F_f + F_b$

dä r_{max} .

Givet: $N_b > 0$

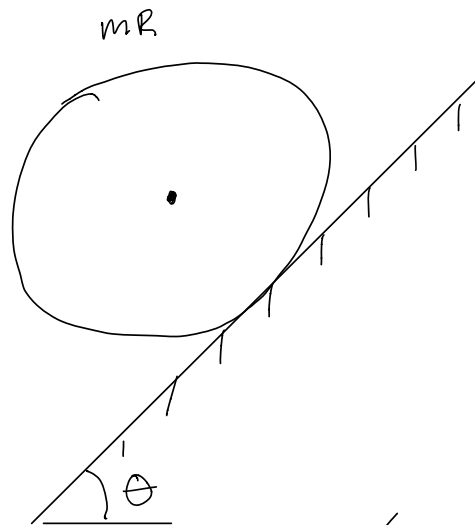
Vid r_{max} gäller

$$\frac{F_f}{F_{tot}} \stackrel{(4)}{=} \frac{\mu}{F_{tot}} (mg \frac{lb}{l} + \frac{F_{tot} \cdot h}{l}) = \frac{(b)}{F_{tot} = m r_{max} = mg} = \frac{lb + \mu h}{l}$$

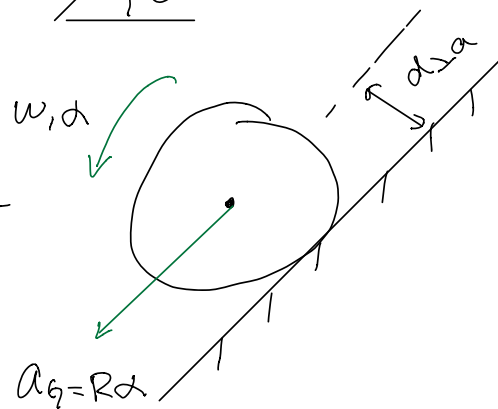
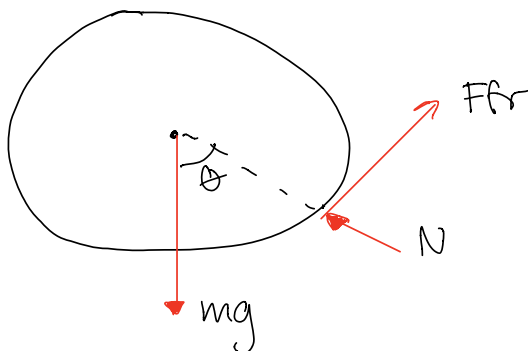
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Givet: Ingen glidning

Sökt: a_G



Frilägg:



Ingen glidning, plant, fixt underlag

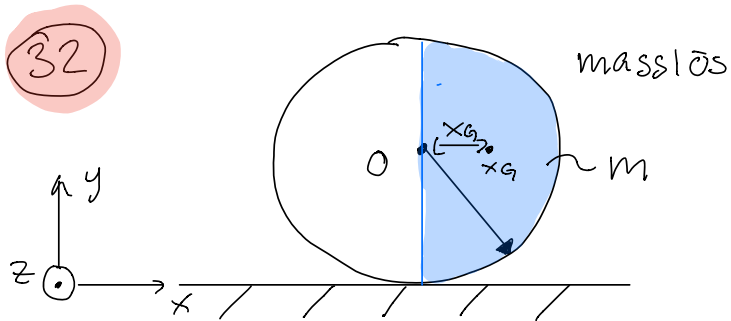
Euler II (skalart)

$$M_A = I_G \alpha + m a_G d_{\perp a}$$

$$\curvearrowleft A: mg R \sin \theta = \underbrace{I_G \alpha}_{\frac{m R^2}{2} (\text{tabell})} + m R \alpha \cdot R \Leftrightarrow$$

$$\Leftrightarrow \alpha = \frac{2 \sin \theta}{3} \cdot \frac{g}{R}$$

$$\therefore a_G = \frac{2 \sin \theta}{3} \cdot g, \quad \swarrow$$



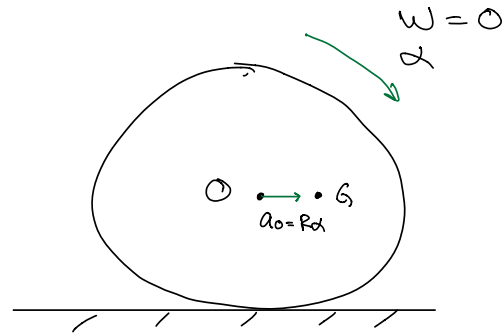
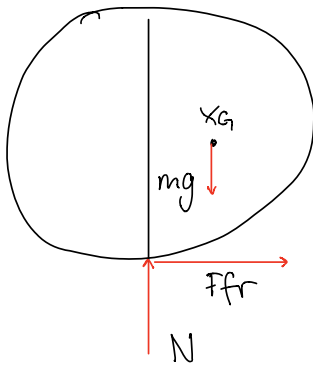
Givet: Släpps från vila vid $t=0$, ingen glidning,

$$x_G = \frac{4R}{3\pi}$$

Sökt: α vid $t=0$, μ_s min så ej börjar glida

$$|F_{fr}| \leq \mu_s N$$

Frilägg:



Euler I:

$$\vec{F} = m\vec{a}_G$$

$$\rightarrow: F_{fr} = ma_{Gx} \quad (1)$$

$$\uparrow: N - mg = ma_{Gy} \quad (2)$$

Euler II: (vektor)

$$\vec{M}_m = I_G \vec{\alpha} + \vec{r}_{mG} \times m\vec{a}_G, \quad \cancel{M}$$

$$\vec{M}_m: -mg x_G \hat{z} = -I_G \alpha \hat{z} + (x_G \hat{x} + R \hat{y}) \times m\vec{a}_G \quad (3)$$

Kinematik

$$\vec{a}_G = \underbrace{\vec{a}_0}_{R\alpha\hat{x}} + \underbrace{\vec{\alpha} \times \vec{r}_{OG}}_{-\alpha\hat{z} \times x_G\hat{x}} - \underbrace{\omega^2 \vec{r}_{OG}}_{=0} = R\alpha\hat{x} - x_G\alpha\hat{y}$$

Insättning i (3) $\Rightarrow \dots \Rightarrow$

$$\alpha = \frac{mg x_G}{\underbrace{I_G + m x_G^2}_{I_0, \text{ Huygens}} + m R^2} = \left[\begin{array}{l} \text{cirkelskiva} \\ \text{M} = 2m \\ I_0 = \frac{1}{2} M R^2 \\ \text{D} \quad m \\ I_0 = \frac{1}{2} \left(\frac{1}{2} M R^2 \right) \\ = \frac{1}{2} m R^2 \end{array} \right]$$

$$= \frac{mg x_G}{\frac{3}{2} m R^2} = \frac{8g}{9\pi R} \quad \curvearrowright$$

(1) \Rightarrow

$$F_{fr} = m a_{Gx} = m R \alpha = \frac{8}{9\pi} mg$$

(2) \Rightarrow

$$N = mg + m a_{Gy} = mg - m x_G \alpha = mg \left(1 - \frac{32}{27\pi^2} \right)$$

Borjar ej glida om

$$|F_{fr}| \leq \mu_s N \Rightarrow \mu_s \geq \frac{|F_{fr}|}{N} = 0,32$$

$$\therefore \mu_{s, \min} = 0,32$$

I en del uppgifter:

$$\ddot{\theta} d\theta = \dot{\theta} d\dot{\theta}$$

Vanliga fel

- Ej tar med F_{fr} som rullar utan glidning ($3/4$ gärdet).
- Fel i kinematiken